



Thesis for the Degree of Master of Engineering

Estimation of surface NO₂ volume mixing ratio using regression models with OMI data

by

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Estimation of surface NO₂ volume mixing ratio using regression models with OMI data (OMI 자료와 회귀모델들을 이용한 지표 이산화질소 혼합비 추정)

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OMI 자료와 회귀모델들을 이용한 지표 이산화질소 혼합비 추정

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요약

본 연구에서는 처음으로 OMI (Ozone Monitoring Instrument) 자료를 활용 하여 세 가지 회귀모델로 13시 45분에서의 지표 이산화질소 혼합비와 웜 평균 지표 이산화질소 혼합비를 대한민국 대도시인 서울, 경기, 대전, 광주에서 추정 하였다. 지점 장비로 측정된 지표 이산화질소 혼합비와 OMI 센서로 부터 획득 한 대류권 이산화질소 수직 칼럼 농도 사이의 관계를 통한 회귀모델과 행성 경 계층 높이, 지표면 압력, 지표면 온도, 지표면 이슬점 온도, 지표면 풍향, 지표 면 풍속 자료가 고려된 회귀모델을 사용하였다. 본 연구의 회귀모델의 회귀 계 수를 결정하기 위한 훈련 기간은 2007년부터 2013년까지이며, 회귀모델의 성 능은 2006년, 2014년의 지점 장비로 측정된 지표 이산화질소 혼합비와 비교를 통하여 평가하였다. 세 가지 회귀모델 중에서 다중 회귀모델이 13시 45분의 지표 이산화질소 혼합비와 월 평균 지표 이산화질소 혼합비 추정에 가장 좋은 성능을 보였다. 검증년도에서 다중 회귀모델로 추정된 13시 45분의 지표 이산 화질소 혼합비와 지점 측정장비로 측정된 지표 이산화질소 혼합비사이의 평균 R (correlation coefficient), 기울기, MB (mean bias), MAE (mean absolute error), RMSE (root mean square error), Percent difference는 각각 0.66. 0.41, -1.36 ppbv, 6.89 ppbv, 8.98 ppbv, 31.50% 이다. 반면에 다른 두 회 귀모델로 추정된 13시 45분의 지표 이산화질소 혼합비와 지점 측정 장비로 측 정된 지표 이산화질소 혼합비 사이의 평균 R. 기울기, MB. MAE, RMSE. Percent difference는 각각 0.75, 0.41, -1.40 ppbv, 3.59 ppbv, 4.72 ppbv,

and 16.59% 이다. 월 평균 지표 이산화질소 혼합비 추정에 있어서는 다중 회 귀모델과 다른 두 회귀모델이 비슷한 성능을 보였다. 세 가지 회귀모델로 추정 된 월 평균 지표 이산화질소 혼합비와 지점 측정 장비로 측정된 지표 이산화질 소 혼합비 사이의 평균 R, 기울기, MB, MAE, RMSE, Percent difference는 각각 0.74, 0.49, -1.90 ppbv, 3.93 ppbv, 5.05 ppbv, 18.76% 이다.



1. Introduction

A main anthropogenic sources of nitrogen dioxide (NO₂) is fossil fuel combustion while natural sources of NO₂ are lightning, forest fire, and soil emissions [IPCC, 2007; Van der et al., 2008]. In particular, since NO₂ is emitted in large quantities in automobile exhaust gas, NO₂ is often used as an indicator for traffic-related air pollution in urban areas [Kharol et al., 2015]. In terms of its effect on human health, Long-term NO_2 exposure can lead to pulmonary depression and respiratory illness [Ackermann-Liebrich et al., 1997; Schindler et al., 1998; Gauderman et al., 2000; Panella et al., 2000; Smith et al., 2000]. In addition, it is precursors of aerosol nitrate, tropospheric ozone, and the hydroxyl radical (OH), the main atmospheric oxidant [Boersma et al., 2009]. Therefore, NO₂ is measured by various methods and chemiluminescence is one of the well known methods for measuring surface NO₂ volume mixing ratio (VMR) [Demerjian, 2000]. In-situ measurement such as the chemiluminescence measurement method is, in general, more accurate than remote sensing techniques, but it requires a number of in-situ instruments to provide the spatial distribution of the NO_2 VMR in high resolution. In recent years, the NO2 vertical column density (VCD) measurements via satellites that can monitor NO₂ of global scale in a short time has been actively conducted. The following various satellite sensors have been utilized to measure these regional or global NO_2 distributions. Space-born sensors that observed global distributions of NO₂ are Global Ozone Monitoring Experiment (GOME) (1995-2003) aboard

Sensing-2 (ERS-2), Scanning Imaging European Remote Absorption Spectrometer for Atmospheric Chartography/Chemistry (SCIAMACHY) aboard Environmental Satellite (Envisat) (2002~), Ozone Monitoring Instrument (OMI) aboard EOS-AURA (2004~), and GOME-2 aboard Meteorological operational satellite (MetOp)-A platform (2007~) and MetOp-B platform (2012~) [Leue et al., 2001; Richter and Burrows, 2002; Martin et al., 2002; Boersma et al., 2004; Boersma et al., 2007; Bucsela et al., 2006]. In many countries, the NO₂ VCD obtained from satellites is can't be directly used for air quality regulation because the surface NO₂ VMR is used for air quality regulation. In recent years, studies have been conducted to investigate the feasibility of estimating the surface NO₂ VMRs using the NO₂ VCD obtained from satellite measurements and the correlation between the NO₂ VCD obtained from satellite measurements and the surface NO₂ VMRs.

ORDÓNEZ et al., (2006) reported the correlation between the troposphere NO_2 VCD and the NO_2 VCD measured by GOME and ground based in-situ device in Milan. Kharol et al., (2015) estimated the annual average ground-level NO_2 concentrations in North America using chemical transport model (GEOS-Chem) data and OMI NO_2 columns. It also reported the annual trend of the estimated ground-level NO_2 concentrations. However, no studies have attempted to estimate the surface NO_2 VMR in higher temporal resolution such as hourly and monthly using the NO_2 VCD measured by satellites.

In this present study, we for the first time estimated the surface NO_2 VMR at a specific time (13:45 Local time; LT) (NO₂ VMR_{ST-estimate}) and

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monthly mean surface NO_2 VMR (NO_2 VMR_{M-estimate}) using two linear regression models and a multiple regression model with the troposphere NO_2 VCD obtained from OMI (Trop NO_2 VCD_{OMI}) in five metropolitan cities. In addition, performances of each regression method were evaluated by comparing the estimated surface NO_2 VMRs with those obtained from in-situ measurement (NO_2 VMR_{In-situ}).



2. Studay area & period



Figure 1. Study areas are located in South Korea.

The study areas were selected where the surface NO_2 VMR was continuously measured in Korean metropolitan cities. Metropolitan cities such as Busan and Incheon where the OMI pixel covers both the sea and cities are excluded since there is no surface NO_2 data available over the sea. Therefore, the selected areas include Seoul, Gyeonggi, Daejeon, and Gwangju. Among the study areas, Seoul, where four OMI pixels exist, is divided into eastern and western areas (West Seoul and East Seoul). The study period is nine years from 2006 to 2014. Seven years (2007 - 2013) are the training period to determine the regression coefficients of the regression models used in this study, whereas two years (2006, 2014) the validation period when for the surface NO_2 VMRs estimated from three regression models with the determined regression coefficients are evaluated via comparison with the in-situ data. The three regression models used in this study are described in detail in Section 3.

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2.1. Data

The data used in this study include Trop $NO_2 VCD_{OMI}$, boundary layer height obtained from Atmospheric Infrared Sounder (AIRS) (BLH_{AIRS}), atmospheric temperature obtained from AIRS (Temp_{AIRS}), pressure obtained from AIRS (Press_{AIRS}), NO₂ VMR_{In-situ}, surface temperature obtained from in-situ measurement (Temp_{In-situ}), surface pressure from in-situ measurement (Press_{In-situ}), surface dew point from in-situ measurement (Dewpoint_{In-situ}), surface wind speed from in-situ measurement (WS_{In-situ}), and surface wind direction from in-situ measurement (WD_{In-situ}). The detailed information of the data are summarized in Table 1.



	Data		Time
Satellite	Trop. NO ₂ VCD	OMI Level3 NO ₂ Daily data (OMNO2d)	13:45
	BLH, Temperature, Pressure	AIRS/Aqua L3 Daily Support Product (AIRS + AMSU) V006 (AIRX3SPD)	13:30
In-situ	Surface NO ₂ VMR Surface Temperature, Surface Pressure, Surface Dewpoint, Surface Wind Speed, Surface Wind Data	Air Korea AWS (Automatic Weather System)	13:00 and 14:00

Table 1. Satellite and In-situ data used in this study.

2.1.1. Ozone Monitoring Instrument (OMI) data

The OMI sensor was launched in July 2004. It measures hyperspectral radiance in ultraviolet and visible wavelength range via push-broom. Since the OMI sensor utilizes the hyperspectral feature, it can improve retrieval accuracy of air pollutants and enable the OMI sensor to do precise radiometric and wavelength calibration for a long time. The OMI sensor has two ultraviolet channels including UV-1 (270 nm - 314 nm) and UV-2 (310 nm - 365 nm). The spectral resolutions of UV-1 and UV-2 are 0.42 nm and 0.45 nm, respectively. The wavelength range and spectral range of visible channel are from 350 nm to 500 nm and 0.63 nm, respectively.

The OMI sensor continues the heritage of the TOMS dataset. The OMI sensor onboard Aura satellite is known as a main sensor to monitor ozone hole and observes key air pollutants including nitrogen dioxide, sulfur dioxide, and aerosols. The Aura is a polar orbiting satellite with an overpass time of 13:45LT.

The Trop NO₂ VCD_{OMIs} were obtained from OMI Level3 NO₂ Daily Data (OMNO2d) provided by NASA Goddard Earth Sciences Data and Information Services Center (http://disc.sci.gsfc.nasa.gov/Aura/data-holdings/OMI). Cloud-screened NO₂ data (Level-3 OMI NO₂ Cloud-Screened Total and Tropospheric Column NO₂ (V003)) are used in this present study (Cloud Fraction < 30 %).

2.1.2. Atmospheric Infrared Sounder (AIRS) data

The BLH_{AIRS}, Temp_{AIRS}, and Press_{AIRS} used in this study were obtained from the AIRS / Aqua L3 Daily Support Product (AIRS + AMSU) 1 degree x 1 degree V006 (AIRX3SPD.00) of NASA Goddard Earth Sciences Data and Information Services Center (http://disc.sci.gsfc.nasa.gov/uui/datasets/AIRX3SPD_V006/summary?keywords= %22AIRS%22). The AIRS / Advanced Microwave Sounding Unit (AMSU) is a sounding suite that aboard the Aqua launched in May 2002 [Aumann et al., 2003; Chahine et al., 2006]. The Aqua is a polar orbiting satellite with an overpass time of 13:30 local time (day and night time) and a spatial resolution of 40 km horizontal at nadir.

2.1.3. In situ NO₂ data

VMR_{In-situ} obtained The NO₂ was from Air Korea (http://www.airkorea.or.kr/last amb hour data). Since NO_2 VMR_{In-situ} is available hourly, the average value of 13:00 LT and 14:00 LT is used to be closer the OMI overpassing time. The Previous study [ORDONEZ et al., 2006], the in-situ measurement sited was grouped into five different NO₂ levels, clean, slightly polluted, average polluted, polluted, and heavily polluted account for many stations which are located close to streets and are exposed to emissions. In addition, the NO₂ data obtained from many in-situ measurement stations in the GOME pixels were averaged, since in-situ measurements are only representative of a small fraction of the satellite ground scene. In this present study, the NO_2 VMR_{In-situs} obtained from in-situ measurements located close to streets were excluded in this study. We used the average of three or more the NO_2 VMR_{In-situ} located at least 2 km distance away from each other.

2.1.4 In situ meteorological data

W ZI

The Temp_{In-situ}, Press_{In-situ}, Dewpoint_{In-situ}, WS_{In-situ}, and WD_{In-situ} used in this study are Automatic Weather System (AWS) data provided by Korea Meteorological Administration (http://sts.kma.go.kr/jsp/home/contents/statistics/newStatisticsSearch.do?menu=SF C&MNU=MNU). Since meteorological data are available hourly, the mean values of the data at 13:00 LT and 14:00 LT are used.

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3. Methodology

In this study, NO₂ VMR_{ST-estimate} and NO₂ VMR_{M-estimate} were estimated using three regression models with Trop NO₂ VCD_{OMI} Table 2 shows the summary of the three models used to estimate NO₂ VMR_{ST-estimate} and NO₂ VMR_{M-estimate}.



	Model	Equation		
M1	13:45LT & Monthly	$NO_2 VMR_{Insitu} = a * Trop NO_2 VCD_{OMI} + b$		
M2	13:45LT & Monthly	$NO_2 VMR_{Insitu} = a^{**}BLHNO_2 VMR_{OMI} + b$		
M3	13:45LT	Section 3 Multiple regression equation (1)		
M4	Monthly	Section 5, Multiple regression equation (1)		

Table 2. The regression models used for surface NO₂ VMR estimation in this study.

Notes: *NO₂ tropospheric vertical column density obtained from OMI.

$$**BLHNO_{2} VMR_{OMI} = \frac{Trop NO_{2} VCD_{OMI} \times *** Gas \ constant R \times *** Temp_{ARS} \times 10^{13}}{****Avogadro \ constant NA \times **** BLH_{ARS} \times **** Press_{ARS}}$$

$$***Gas \ constant = 8.314472 \ m^{3} pa \ k^{-1} mol^{-1}$$

****Boundary layer mean temperature (K) obtained from AIRS. ***** $Avogadroconstant = 6.022 \times 10^{23} mol^{-1}$ *****Boundary layer height (m) obtained from AIRS. *****Boundary layer mean pressure (pa) obtained from AIRS.



3.1 M1

M1 is the liner regression equation where Trop NO₂ VCD_{OMI} used as an independent variable. Figure 2 shows the linear regression between Trop NO₂ VCD_{OMI} and NO₂ VMR_{In-situ} at 13:45LT during the training period. In figure 2, R^2 (coefficient of determination), slope, and intercept are 0.47, 0.80 and 11.47, respectively. Figure 3 shows the linear regression between monthly mean Trop NO₂ VCD_{OMI} and monthly mean NO₂ VMR_{In-situ} during the training period. In figure 3, R^2 , slope, and intercept are 0.62, 0.77, and 10.95, respectively. The final form of the equation M1 to estimate NO₂ VMR_{ST-estimates} is shown Table 4. Whereas, the final form of the equation M1 to estimate NO₂ VMR_{M-estimates} is shown Table 5.



Figure 2. Correlation between Trop $NO_2 VCD_{OMI}$ and $NO_2 VMR_{In-situ}$ to determine regression coefficient for the equation, M1 for the training period between 2007 and 2013.



Figure 3. Correlation between monthly mean Trop $NO_2 VCD_{OMI}$ and monthly mean $NO_2 VMR_{In-situ}$ to determine regression coefficient for the equation, M1 for the training period between 2007 and 2013.

3.2 M2

Assuming that Trop NO₂ VCD_{OMI} is mostly present within the planetary boundary layer (PBL), the relationship between Trop NO₂ VCD_{OMI} and the surface NO₂ VMR may change as the planetary boundary layer varies. To reflect the BLH in the regression equation, Trop NO₂ VCD_{OMI} is first divided by BLH_{AIRS} to calculate the NO₂ concentration in the PBL and then converted to the NO₂ mixing ratio in PBL (BLH NO₂ VMR_{OMI}) using Temp_{AIRS} and Press_{AIRS} (see Table 2). Figure 4 shows the linear regression between BLH NO₂ VMR_{OMI} and NO₂ VMR_{In-situ} at 13:45LT during the training period. In figure 4, R², slope and intercept are 0.38, 1.58, and 14.30, respectively. Figure 5 shows the linear regression between monthly mean BLH NO₂ VMR_{OMI} and monthly mean NO₂ VMR_{In-situ} during the training period. In figure 5, R², slope and intercept are 0.59, 1.71, and 12.75, respectively. The final form of the equation M2 to estimate NO₂ VMR_{ST-estimates} is shown Table 4. Whereas, the final form of the equation M2 to estimate NO₂ VMR_{M-estimates} is shown Table 5.



Figure 4. Correlation between BLH NO_2 VMR_{OMI} at specific time(13:45LT) and NO_2 VMR_{In-situ} to determine regression coefficient for the equation, M2 for the training period between 2007 and 2013.



Figure 5. Correlation between monthly mean BLH $NO_2 VMR_{OMI}$ and monthly mean $NO_2 VMR_{In-situ}$ to determine regression coefficient for the equation, M2 for the training period between 2007 and 2013.

3.3 M3 & M4

M3 M4 are multiple regression equations to estimate NO₂ and VMR_{ST-estimates} and NO₂ VMR_{M-estimates}. Multiple regression equation consists dependent variable, independent variables, and their regression of а coefficients. For the independent variable candidates, in addition to Trop NO₂ VCD_{OMI} and BLH_{AIRS}, meteorological factors (surface temperature, surface dew point, atmospheric pressure, wind direction, and wind speed) are used as independent variable candidates for the multiple regression equation in this present study. In previous study [Xue and Yin, 2014], these meteorological factors were also used for the multiple regression equation as independent variable candidates to estimate surface SO₂ concentration in Shanghai, China.

The multiple regression equation can be defined as the following equations:

$$\hat{y} = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n + \epsilon \tag{1}$$

where \hat{y} and β_0 are dependent variable (NO₂ VMR_{In-situ}) and regression coefficient, x₁, x₂,...x_n are the candidates of independent variables (Trop NO₂ VCD_{OMI}, Dewpoint_{In-situ}, Press_{In-situ}, Temp_{In-situ}, BLH_{AIRS}, WS_{In-situ}, WD_{In-situ}), β_1 , β_2 , ..., β_n are the regression coefficients of the independent variables, and ε is the difference between observations (NO₂ VMR_{In-situ}) and estimates values (NO₂ VMR_{estimates}). The regression coefficients can be estimates by the least square fitting (Equation 2).

$$\sum_{j=1}^{m} \epsilon_j^2 = \sum_{j=1}^{m} (y_j - \hat{y_j})^2$$
(2)

Where y_j is observed value with m numbers of data points. By minimizing the sum of ε^2 , regression coefficients can be derived. To determine independent variable (x_n) and regression coefficients (β_n) included in the final form of the equations M3 and M4, we considered variation inflation factor (VIF) and p-value to ensure statistical significance of those variables and their coefficient. First, we examined the VIF that explains the multicollinearity of an independent variable candidate with regard to other independent variable candidates. The VIF of the j-th independent variable is expressed as:

$$VIF(x_j) = \frac{1}{1 - R_j^2} \tag{3}$$

Where R_j^2 is the coefficient of determination for the regression of x_j against the other (a regression that does not involve the dependent variable j). The VIF indicates how much x_j is correlated with the variables. A candidate for independent variables with a very high VIF can be considered redundant and should be removed from the multiple regression equations. The candidates for independent variables that do not satisfy the criterion VIF < 10 [Kutner et al., 2004], were excluded from the independent

variables. p-value was also used to select independent variables. The highest, still statistically significant p-level was shown by Sellke et al. (2001) to be 5%. Among the independent variables that satisfy the VIF criterion, those that also satisfy the p-value less than 0.05 (p-value < 0.05) are selected as final independent variables in the multiple regression equations. The lists of independent variables selected for the equations M3 and M4 are shown in Table 3. The final form of the equation M3 to estimate NO₂ VMR_{ST-estimates} is shown Table 4. Whereas, the final form of the equation M4 to estimate NO₂ VMR_{M-estimates} is shown Table 5.



	Final included independent variables	p-value	VIF
	Trop NO ₂ VCD _{OMI}	0	1.26
	****TempIn-situ	0.000032	7.02
	*Dewpoint _{In-situ}	0.000306	7.16
M3	**Press _{In-situ}	0.009981	3.14
	BLHAIRS	1.73×10^{-15}	1.12
	***WS _{In-situ}	3.86×10^{-133}	1.33
	****WD _{In-situ}	1.7493×10^{-38}	1.07
M4	Trop NO ₂ VCD _{OMI}	2.4832×10^{-89}	1.64
	*Dewpoint _{In-situ}	0.000421	6.47
	**Press _{In-situ}	0.034582	6.65
	BLH _{AIRS}	0.000834	2.32
	$***WS_{In-situ}$	3.86×10^{-133}	1.59
	****WD _{In-situ}	1.699×10^{-7}	1.25

Table 3. Final independent variables included in multiple regression equations (M3 and M4).

***Surface wind speed

****Surface wind direction

*****Surface temperature

Table 4. Final form of the regression models used for surface NO_2 VMR at specific time estimations and R^2 obtained from the regression between NO_2 VMR_{In-situ} and each model's independent variable for the training period.

		Equation	R^2
13:45LT	M1	$NO_2 VMR_{ST-estimate} = 1.71 \times Trop NO_2 VCD_{OMI} - 0.68$	0.47
	M2	$NO_2 VMR_{ST-estimate} = 4.19 \times BLHNO_2 VMR_{OMI} + 1.57$	0.38
	M3	$\begin{split} NO_2 \ VMR_{ST-estimate} &= 0.000602 \times \mathit{Trop} \ NO_2 \ VCD_{OMI} \\ &- 0.000107 \times \mathit{Temp}_{Insitu} - 0.000083 \times \mathit{Dewpoint}_{Insitu} \\ &+ 0.000061 \times \mathrm{Pr}ess_{Insitu} - 0.000002 \times \mathit{BLH}_{AIRS} \\ &- 0.002435 \times \mathit{WS}_{Insitu} + 0.001190 \times \mathit{WD}_{Insitu} - 0.039996 \end{split}$	0.47

Table 5. Final form of the regression models used for monthly mean surface NO_2 VMR estimations and R^2 obtained from the regression between NO_2 VMR_{In-situ} and each model's independent variable for the training period.



Table 4 and Table 5 show equations of M1, M2, M3, and M4, which reflect the regression coefficients determined

from the training period.



4. Results

4.1 Daily estimation

Figure 6 shows daily variations of NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} estimated at 13:45LT using the M1, M2 and M3 of Table 4 in from West Seoul and East Seoul. The NO₂ VMR_{ST-estimates} are estimated using M1, M2, and M3 in Table 4 with the inputs of independent variable data for the years 2006 and 2014, the validation period. A slightly large difference in magnitude is found between NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} obtained from M3 compared to those between NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} obtained from M1 and M2. However, NO₂ VMR_{ST-estimates} obtained from M3 showed good agreement with NO₂ VMR_{In-situ} in hourly pattern. The graph showing the same as figure 6.

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Figure 6. Time series of NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} estimates by M1, M2 and M3 in study areas for the period 2006 ((a), (c), (e), (g), and (i)), and 2014 ((b), (d), (f), (h), and (j)).



Figure 7. (a) R, (b) slope, (c) MB, (d) MAE, (e) RMSE, and (f) percent difference between NO₂ VMR_{ST-estimates} against NO₂ VMR_{In-situ} in 2006 and 2014.

Figure 7 shows the (a) R (correlation coefficient), (b) slope, (c) mean bias (MB), (d) mean absolute error (MAE), (e) root mean square error (RMSE) and (f) percent difference between NO₂ VMR_{ST-estimates} and NO₂ VMR_{In-situ} in validation period (2006 and 2014). The R between NO₂ VMR_{ST-estimates} obtained from M1 and NO₂ VMR_{In-situ} ranges from 0.49 to 0.71, showing better agreement than that of NO₂ VMR_{ST-estimates} from M2 (0.47 < R < 0.65). M3 showed the best correlation with NO₂ VMR_{In-situ} (0.67 \leq R \leq 0.90) among the three methods. The slopes between NO_2 VMR_{In-situ} and NO_2 VMR_{ST-estimates} from both M1 and M2 are close 1 in East Seoul, whereas they are lower the other cities. The MB between NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} from M1, M2, and M3 range from -7.74 to 5.80 ppbv. In all study areas, MAE (5.79 ppbv < MAE < 8.25 ppbv) of M3 is lower than those (6.58 ppbv < MAE < 11.41 ppbv) of M1 and M2, which means that NO₂ VMR_{ST-estimates} estimated from M3 show good agreement with NO₂ VMR_{In-situ} in the magnitude. RMSE between NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} from M3 is found to be lower than those between NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} from M1 and M2. The NO₂ VMR_{ST-estimates} by M3 showed the lowest RMSE in all study areas (7.21 ppbv < RMSE <11.37 ppbv). In addition, percent differences between NO₂ VMR_{ST-estimates} estimated from M3 and NO₂ VMR_{In-situ} were lower in all study areas than estimated values by M1 and M2. In estimating NO₂ VMR_{ST-estimates}, M3, which is a multiple regression method with inputs of various independent variables, generally showed good statistical performance except for MB.

4.2 Monthly estimation

Figure 8 shows temporal variations of NO₂ VMR_{M-estimates} and monthly mean NO₂ VMR_{In-situ} estimated using the M1, M2 and M4 of Table 5 in from West Seoul and East Seoul. The NO2 VMR_{M-estimates} are obtained from M1, M2 and M4 in Table 5 with the inputs of monthly mean independent variables during the validation period (see the detailed input data in Section 2.1). Figure 8 shows a good agreement between the estimated NO_2 VMR_{M-estimates} and monthly mean NO₂ VMR_{In-situ} in the temporal pattern. However, we found a large difference between NO₂ VMR_{In-situ} and NO₂ VMR_{M-estimates} in the period when there was a change difference in NO₂ VMR_{M-estimates} between the previous and the following months. For example, there was no models that calculated NO₂ VMR_{M-estimates} that were similar to NO₂ VMR_{In-situ} in December 2006 which changes largely compared to that in November 2006. NO₂ VMR_{In-situ} (NO₂ VMR_{M-estimates} from M1, M2, and M4) in November and December in 2006 are 19.32 ppbv (15.94, 17.96, and 17.62 ppbv) and 30.30 ppbv (15.94, 17.96, and 17.62 ppbv) in Daejeon, 15.26 ppbv (12.29, 13.87, and 18.09 ppbv) and 32.55 ppbv (12.73, 14.57, and 18.46 ppbv) in Gwangju, 29.31 ppbv (25.86, 25.97, and 22.35 ppbv) and 40.64 ppbv (29.91, 29.15, and 26.85 ppbv) in Gyeonggi, and 31.25 ppbv (22.80, 24.55, and 23.64 ppbv) and 45.93 ppbv (28.65, 28.92, and 26.49 ppbv) in West Seoul. Especially in West Seoul, There are several periods when NO₂ VMR_{In-situ} changes rapidly compared to the previous month. The NO₂ VMR_{M-estimates} obtained from the three models are in poor agreement with NO₂ VMR_{In-situ} in monthly pattern. As described in Section 2, despite the use of NO_2 VMR_{In-situ} located away from the streets, the in-situ measurement sites in West Seoul are located closer to the streets than the in-situ measurement sites in Daejeon and Gwangju. For this reason, there thought to be more periods when NO_2 VMR_{In-situ} changes rapidly compared to the previous month. It is difficult to estimate the rapid change of NO_2 VMR near NO_2 source by regression models that reflect the relationship between the in-situ measurements and the OMI sensor covering both source and non-source areas in a single pixel.













Figure 8. Time series of NO₂ $VMR_{In-situ}$ and NO₂ $VMR_{M-estimates}$ estimates by M1, M2, and M4 for the period 2006 and 2014.



Figure 9. (a) R, (b) slope, (c) MB, (d) MAE, (e) RMSE, and (f) percent difference between NO₂ VMR_{M-estimates} against monthly mean NO₂ VMR_{In-situ} in 2006 and 2014.

Figure 9 shows the (a) R, (b) slope, (c) MB, (d) MAE, (e) RMSE and (f) percent difference between NO₂ VMR_{M-estimates} and monthly mean NO₂ VMR_{In-situ} in 2006 and 2014. In general, NO₂ VMR_{M-estimates} showed better agreement with NO₂ VMR_{In-situ} than the NO₂ VMR_{ST-estimates}. R between NO₂ VMR_{M-estimates} obtained from M1, M2 and M4 and monthly mean NO₂ VMR_{In-situ} areas range from 0.68 to 0.82 in all areas. MB was close to 0 in most study areas. MAE was less than 5 ppbv in Daejeon, Gwangju, Gyeonggi, and East Seoul where there are good agreements between NO₂ VMR_{M-estimates} from M1, M2, and M4 and monthly mean NO₂ VMR_{M-estimates} from M1, M2, and M4 and monthly mean NO₂ VMR_{M-estimates} from M1, M2, and M4 and monthly mean NO₂ VMR_{In-situ}, whereas MAEs in West Seoul ranges from 5.66 to 6.79. RMSEs between NO₂ VMR_{In-situ} and NO₂ VMR_{M-estimates} from M1, M2, and M3 are found to be lower than 7 ppbv in study areas except for West seoul. In addition, the three models showed percent difference of less than 30% except for estimated value from M1 in Gwangju.

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5. Discussion

In previous study [ORDÓNEZ et al., 2006], tropospheric NO₂ VCDs obtained from GOME were compared with tropospheric NO₂ VCDs calculated using both NO₂ concentrations obtained from in-situ measurements and Model of Ozone and Related Tracers 2 (MOZART-2). There are also several previous studies estimating surface NO₂ VMR using satellite data [Lamsal et al., 2008; Kharol et al., 2015]. Among them, Kharol et al. (2006) estimated the annual variation of ground-level NO₂ concentrations using both GEOS-Chem data and OMI data. However, in this present study, NO₂ VMR_{ST-estimates} and NO₂ VMR_{M-estimates} were estimated for the first time in higher temporal resolution using the three regression models with the inputs of Trop NO₂ VCD_{OMI}.

- Estimation of surface NO₂ VMRs of a specific time (13:45LT).
 - ✓ Among the three regression models, the multiple regression model M3, showed the best performance in estimating NO₂ VMR_{ST-estimatie}. In estimation of NO₂ VMR_{ST-estimatie}, the linear regression model (M2), in which BLH is used also as an independent variable in addition to Trop NO₂ VCD_{OMI}, shows performance comparable with that of the model (M1) which uses Trop NO₂ VCD_{OMI} as the only independent variable. The BLH varies with latitude [Zeng et al., 2004]. The BLH is not well reflected by the latitude change since the spatial resolution of the AIRS used in this study is larger than the spatial resolution of OMI. We expected better results by using BLH data obtained from

Lidar or by correcting spatial resolution difference between OMI and AIRS.

- ✓ A slightly large differences in magnitude were found between NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} obtained from M1, M2 and M3, while there were good agreements in daily patterns of NO₂ between NO₂ VMR_{In-situ} and NO₂ VMR_{ST-estimates} obtained from M1, M2 and M3 (Figure 4).
- ✓ In terms of statistical evaluation via comparison between NO₂ VMR_{ST-estimates} and NO₂ VMR_{In-situ}, M3 showed in general the best performance.
- Estimation of monthly mean surface NO₂ VMRs of a specific time (13:45LT).
 - ✓ We found a good agreement between the estimated NO₂ VMR_{M-estimates} and monthly mean NO₂ VMR_{In-situ} in the temporal pattern (Figure 8). However, it was shown that a large difference between NO₂ VMR_{In-situ} and NO₂ VMR_{M-estimates} in the period when there was a change difference in NO₂ VMR_{M-estimates} between the previous and the following months. Despite the use of NO₂ VMR_{In-situ} located away from the streets, the in-situ measurement sites in West Seoul are located closer to the streets than the in-situ measurement sites in Daejeon and Gwangju. For this reason, there thought to be more periods when NO₂ VMR_{In-situ} changes rapidly compared to the previous month. It is difficult to estimate the rapid change of NO₂ VMR near NO₂ source by regression models that reflect the

relationship between the in-situ measurements and the OMI sensor covering both source and non-source areas in a single pixel.

- ✓ In terms of statistical evaluations, performances in estimating NO₂ VMR_{M-estimates} using three regression models (M1, M2, and M4) were found to be similar (Figure 9).
- ✓ NO₂ VMR_{M-estimates} shows better agreement with the NO₂ VMR_{In-situ} than NO₂ VMR_{ST-estimates}. The reason for the better performances in the monthly mean estimation could be attributed to the reduced errors in monthly mean OMI data [OMI Team, 2009] and also fewer occasions with sudden monthly changes in NO₂ VMR_{In-situ} than rapid daily changes in NO₂ VMR_{In-situ}.

In this study, it is expected that the regression methods used to estimate the surface NO_2 VMR using Trop NO_2 VCD_{OMI} will be useful in providing information on surface NO_2 VMR in metropolitan cites. For future researches, the estimation of surface NO_2 VMR can be attempted in higher time resolution with geostationary satellite sensors (e.g., geostationary environmental monitoring spectrometer (GEMS), tropospheric emissions: monitoring of pollution (TEMPO), and sentinel-4).

6. Conclusions

In this study, NO₂ VMR_{ST}-estimates and NO₂ VMR_M-estimates were estimated for the first time using three regression models in four metropolitan cities for the two years period 2006 and 2014. Multiple regression model (M3) is found to show the best performance in estimating NO₂ VMR_{ST-estimates} in all cities. For the surface NO_2 estimates at the specific time (13:45LT), there are generally better R, MAE, RMSE, and percent difference between NO2 VMR_{ST-estimates} from M3 and NO₂ VMR_{In-situ} than those between NO₂ VMR_{ST-estimates} from other two models (M1 and M2) and NO₂ VMR_{In-situ}. In comparison of the performances between monthly surface NO₂ VMR estimates and those at specific time, agreement between NO₂ VMR_{In-situ} and NO2 VMR_{M-estimates} found to be better than that between NO2 VMR_{In-situ} and NO2 VMR_{ST-estimates}. In estimating NO2 VMR_{M-estimates}, three regression models (M1, M2, and M4) showed similar performances. In estimating daily surface NO₂ VMR variation and monthly surface NO₂ VMR variation, when surface NO2 VMR rapidly change, difference between surface NO2 VMR estimated from all models and NO₂ VMR_{In-situ} is found to be large. For the future studies, using higher spatial resolution satellites is expected to improve the relationship with in-situ measurements. In addition, independent variables that can estimate the rapid change of surface NO₂ VMR should be investigated.

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